

Then

$$\sqrt{T} \operatorname{vec}(\hat{\Phi}_i - \Phi_i) \xrightarrow{d} N(0, G_i \mathcal{Y}_{\hat{\alpha}} G_i'), \quad i = 1, 2, \dots, \quad (3.7.5)$$

where

$$G_i := \frac{\partial \operatorname{vec}(\Phi_i)}{\partial \alpha'} = \sum_{m=0}^{i-1} J(A')^{i-1-m} \otimes \Phi_m.$$

$$\sqrt{T} \operatorname{vec}(\hat{\Psi}_n - \Psi_n) \xrightarrow{d} N(0, F_n \mathcal{Y}_{\hat{\alpha}} F_n'), \quad n = 1, 2, \dots, \quad (3.7.6)$$

where $F_n := G_1 + \dots + G_n$.

If $(I_K - A_1 - \dots - A_p)$ is nonsingular,

$$\sqrt{T} \operatorname{vec}(\hat{\Psi}_\infty - \Psi_\infty) \xrightarrow{d} N(0, F_\infty \mathcal{Y}_{\hat{\alpha}} F_\infty'), \quad (3.7.7)$$

where $F_\infty := \underbrace{(\Psi'_\infty, \dots, \Psi'_\infty)}_{p \text{ times}} \otimes \Psi_\infty$.

$$\sqrt{T} \operatorname{vec}(\hat{\Theta}_i - \Theta_i) \xrightarrow{d} N(0, C_i \mathcal{Y}_{\hat{\alpha}} C_i' + \bar{C}_i \mathcal{Y}_{\hat{\sigma}} \bar{C}_i'), \quad i = 0, 1, 2, \dots, \quad (3.7.8)$$

where

$$C_0 := 0, \quad C_i := (P' \otimes I_K) G_i, \quad i = 1, 2, \dots, \quad \bar{C}_i := (I_K \otimes \Phi_i) H, \quad i = 0, 1, \dots,$$

and

$$H := \frac{\partial \operatorname{vec}(P)}{\partial \sigma'} = \mathbf{L}'_K \{ \mathbf{L}_K [(I_K \otimes P) \mathbf{K}_{KK} + (P \otimes I_K)] \mathbf{L}'_K \}^{-1}$$

$$= \mathbf{L}'_K \{ \mathbf{L}_K (I_{K^2} + \mathbf{K}_{KK}) (P \otimes I_K) \} \mathbf{L}'_K \}^{-1}.$$

$$\sqrt{T} \operatorname{vec}(\hat{\Xi}_n - \Xi_n) \xrightarrow{d} N(0, B_n \mathcal{Y}_{\hat{\alpha}} B_n' + \bar{B}_n \mathcal{Y}_{\hat{\sigma}} \bar{B}_n'), \quad (3.7.9)$$

where $B_n := (P' \otimes I_K) F_n$ and $\bar{B}_n := (I_K \otimes \Psi_n) H$.

If $(I_K - A_1 - \dots - A_p)$ is nonsingular,

$$\sqrt{T} \operatorname{vec}(\hat{\Xi}_\infty - \Xi_\infty) \xrightarrow{d} N(0, B_\infty \mathcal{Y}_{\hat{\alpha}} B_\infty' + \bar{B}_\infty \mathcal{Y}_{\hat{\sigma}} \bar{B}_\infty'), \quad (3.7.10)$$

where $B_\infty := (P' \otimes I_K) F_\infty$ and $\bar{B}_\infty := (I_K \otimes \Psi_\infty) H$.

Finally,

$$\sqrt{T} (\hat{\omega}_{jk,h} - \omega_{jk,h}) \xrightarrow{d} N(0, d_{jk,h} \mathcal{Y}_{\hat{\alpha}} d'_{jk,h} + \bar{d}_{jk,h} \mathcal{Y}_{\hat{\sigma}} \bar{d}'_{jk,h})$$

$$j, k = 1, \dots, K; h = 1, 2, \dots, \quad (3.7.11)$$

where

$$d_{jk,h} := \frac{2}{\operatorname{MSE}_j(h)^2} \sum_{i=0}^{h-1} [\operatorname{MSE}_j(h) (e'_j \Phi_i P e_k) (e'_k P' \otimes e'_j) G_i$$

$$- (e'_j \Phi_i P e_k)^2 \sum_{m=0}^{h-1} (e'_j \Phi_m \mathcal{Y}_u \otimes e'_j) G_m]$$

with $G_0 := 0$ and

$$y_t = A_1 y_{t-1} + u_t + M_1 u_{t-1}. \quad (7.2.13)$$

Assuming we have a sample y_1, \dots, y_T generated by this process and defining

$$\mathfrak{A}_p := \begin{bmatrix} I_K & 0 & & \dots & & 0 & 0 \\ -A_1 & I_K & & & & 0 & 0 \\ -A_2 & -A_1 & & & & 0 & 0 \\ \vdots & \vdots & \ddots & & & \vdots & \vdots \\ -A_p & -A_{p-1} & & & & 0 & 0 \\ 0 & -A_p & & & & 0 & 0 \\ \vdots & & \ddots & & & \vdots & \vdots \\ 0 & 0 & & & & I_K & 0 \\ 0 & 0 & \dots & -A_p & \dots & -A_1 & I_K \end{bmatrix} \quad (7.2.14)$$

we get

$$\mathfrak{A}_1 \begin{bmatrix} y_1 \\ \vdots \\ y_T \end{bmatrix} + \begin{bmatrix} -A_1 y_0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \overline{\mathfrak{M}}_1 \begin{bmatrix} u_0 \\ u_1 \\ \vdots \\ u_T \end{bmatrix}.$$

Hence, for given, fixed presample values y_0 ,

$$\mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_T \end{bmatrix} \sim N(\mathfrak{A}_1^{-1} \mathbf{y}_0, \mathfrak{A}_1^{-1} \overline{\mathfrak{M}}_1 (I_{T+1} \otimes \mathcal{Z}_u) \overline{\mathfrak{M}}_1' \mathfrak{A}_1'^{-1}), \quad (7.2.15)$$

where

$$\mathbf{y}_0 := \begin{bmatrix} A_1 y_0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

The corresponding likelihood function conditional on y_0 is

$$\begin{aligned} l(A_1, M_1, \mathcal{Z}_u | \mathbf{y}, y_0) & \propto |\mathfrak{A}_1^{-1} \overline{\mathfrak{M}}_1 (I_{T+1} \otimes \mathcal{Z}_u) \overline{\mathfrak{M}}_1' \mathfrak{A}_1'^{-1}|^{-1/2} \\ & \times \exp\{-\frac{1}{2}(\mathbf{y} - \mathfrak{A}_1^{-1} \mathbf{y}_0)' \mathfrak{A}_1' [\overline{\mathfrak{M}}_1 (I_{T+1} \otimes \mathcal{Z}_u) \overline{\mathfrak{M}}_1']^{-1} \mathfrak{A}_1 (\mathbf{y} - \mathfrak{A}_1^{-1} \mathbf{y}_0)\} \\ & = |\overline{\mathfrak{M}}_1 (I_{T+1} \otimes \mathcal{Z}_u) \overline{\mathfrak{M}}_1'|^{-1/2} \exp\{-\frac{1}{2}(\mathfrak{A}_1 \mathbf{y} - \mathbf{y}_0)' [\overline{\mathfrak{M}}_1 (I_{T+1} \otimes \mathcal{Z}_u) \overline{\mathfrak{M}}_1']^{-1} \\ & \quad \times (\mathfrak{A}_1 \mathbf{y} - \mathbf{y}_0)\}, \end{aligned} \quad (7.2.16)$$

where $|\mathfrak{A}_1| = 1$ has been used.

With the same arguments as in the pure MA case a simple approximation is obtained by setting $u_0 = y_0 = 0$. Then we get